Milestones

October

7th - off (fall break)

14th -

21st - Everything ordered,

28th - begin assembly of what has arrived, Milestones/Gantt Chart Review

November

4th - continue assembly

11th - have most parts

18th - wrap up construction of prototype #1 (tethered)

25th - motor and sensor testing

December

2nd - have robot hardware complete, most robot software done, have a kicking robot

9th - off (finals week)

16th - off

23rd - off

30th - off

January

6th - have a walking robot

13th - robot can walk well, begin beacon navigation software, prep to make robot untethered

20th - no meeting (MLK day)

27th - make robot untethered (prototype #2)

February

3rd - begin testing on uneven terrain, robot can fulfill all but 1-2 scope requirements

10th - next time weather permits, begin testing for the real course

17th - no meeting (Presidents day)

24th - “Optional next steps”: rebuild robot out of fiberglass infused ABS

March

3rd -

10th - off (spring break)

17th - begin presentation, robot can fulfill all scope requirements

24th -

31st - mostly done with presentation board

April

7th - done with everything everything, print presentation board

14th - prep for design day

17th - Design Day